## **Color Segmentation**

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Abbreviation:color-segNumber of instances:3Number of variables:21000, 424720Number of labels:3, 4Number of factors:2Order:2Function type:potts

**Description** The color-seg instances describe the segmentation of 2D color images. A discrete random variable with k labels is introduced for each pixel and their configuration is interpreted as the segmentation of the image into k disjoint sets. The quality of the segmentation is characterized by an energy function that trades off boundary against region terms given some sparse external labels of the desired segments.

**Objective / Learning** The energy to be minimized takes the following form:

$$E(\mathbf{x}) = \sum_{i \in \mathcal{V}} \phi_i(x_i) + \sum_{\{i,j\} \in \mathcal{N}} \phi_{ij}(x_i, x_j)$$
(1)

The unary region terms  $\phi_i(x_i)$  are defined in term of the RGB distributions  $\mathcal{H}_a, a = l_1, \dots, l_k$  for the k segments as

$$\phi_i(x_i) = -\log p(x_i = a | \mathcal{H}_a) \tag{2}$$

The distributions are estimated from the externally provided labels.

The pairwise boundary terms  $\phi_{ij}(x_i, x_j)$  operate on a 8-pixel neighborhood  $\mathcal{N}$ . They take the form of a Generalized Potts model:

$$\phi_{ij}(x_i, x_j) = \begin{cases} \lambda_1 + \lambda_2 \exp\left(\frac{-g^2(i,j)}{2\sigma^2}\right) \frac{1}{\operatorname{dist}(i,j)} & \text{if } x_i \neq x_j \\ 0 & \text{if } x_i = x_j \end{cases}$$
(3)

The terms g(i, j) and dist(i, j) represent the distance in the RGB values and the spatial distance respectively. The following parameter settings are used:  $\lambda_1 = 5$ ,  $\lambda_2 = 100$ , and  $\sigma = 5$ .

## References